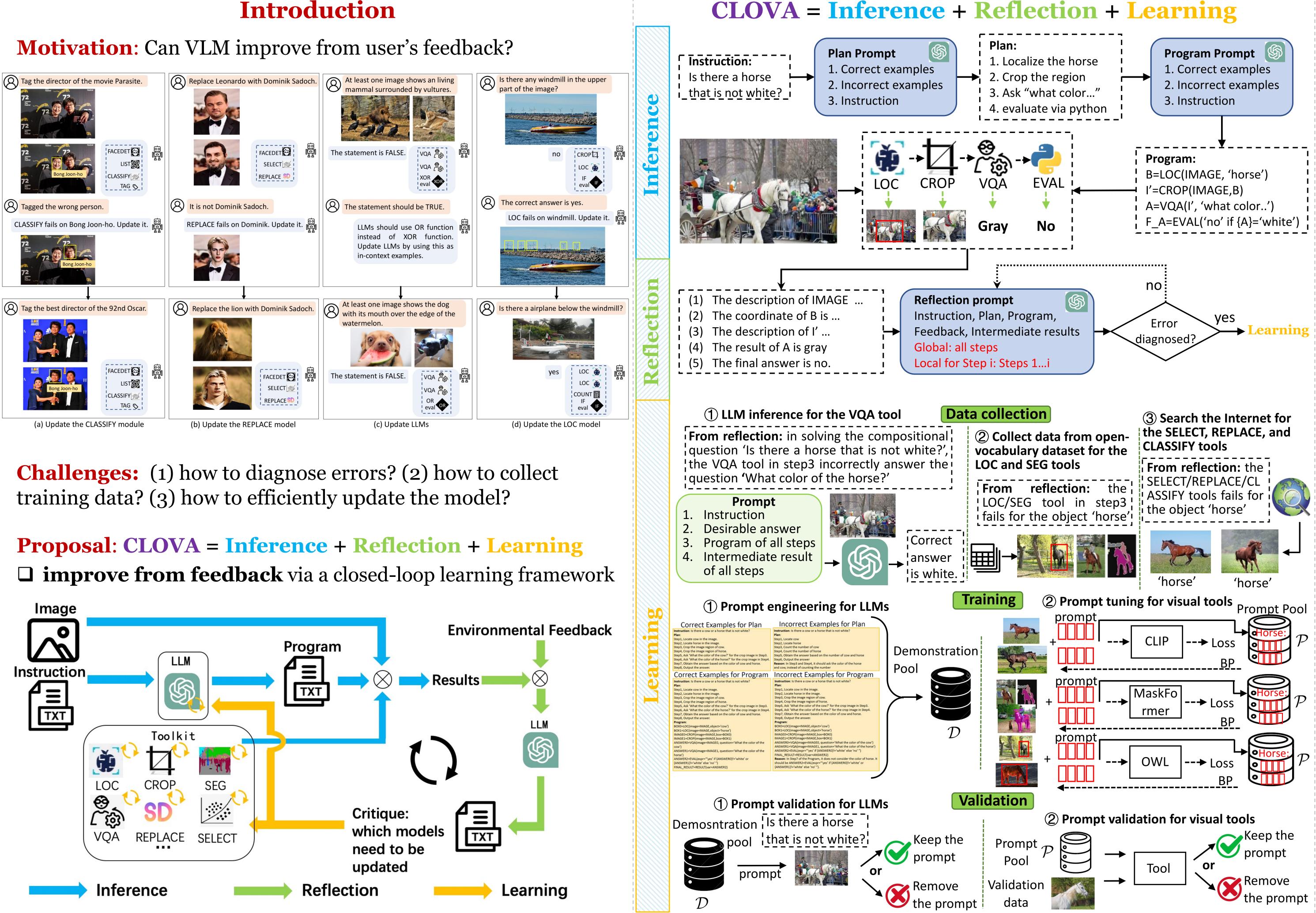
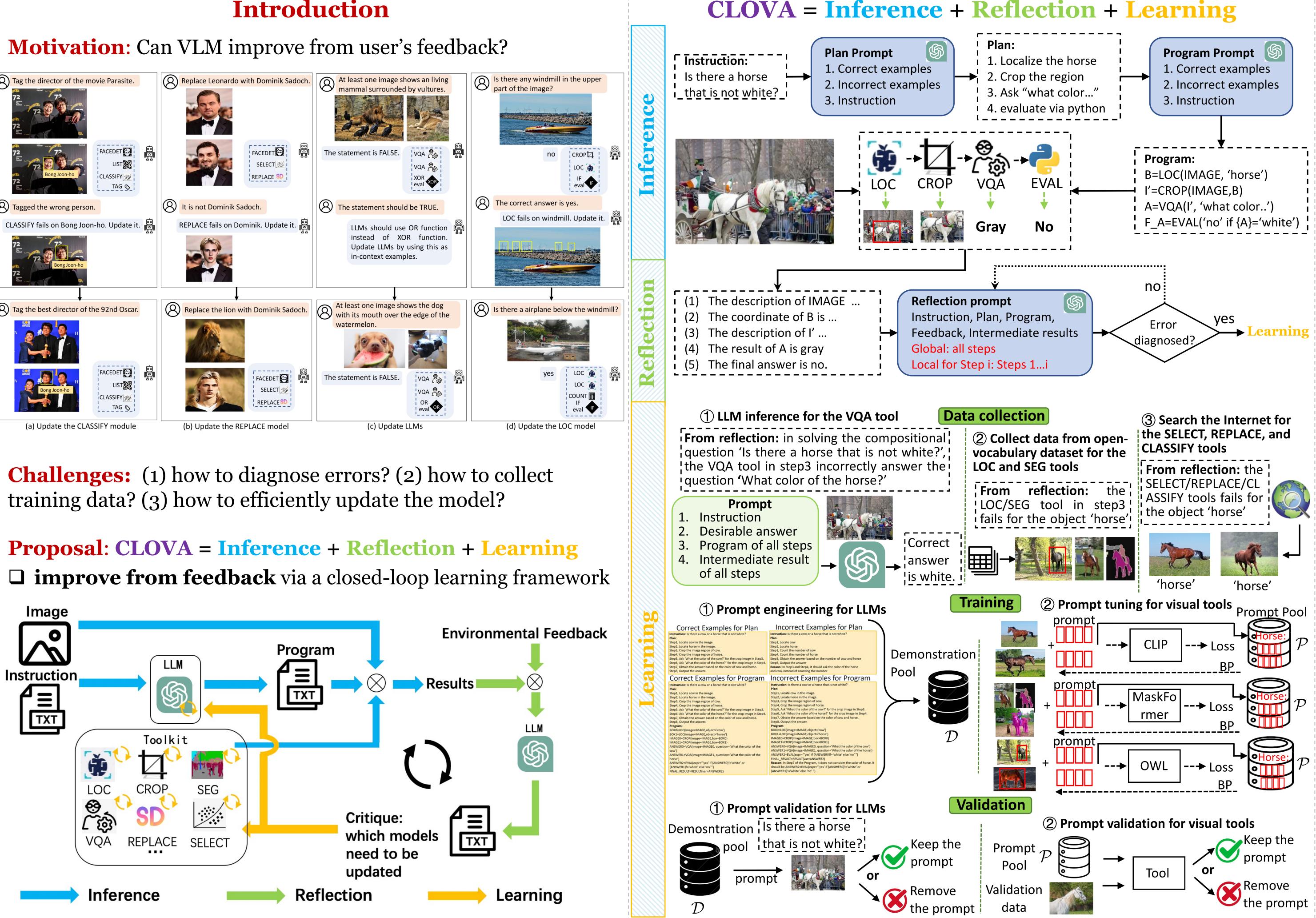






### Introduction





# **CLOVA: A Closed-Loop Visual Assistant with Tool Usage and Update** Zhi Gao, Yuntao Du, Xintong Zhang, Xiaojian Ma, Wenjuan Han, Song-Chun Zhu, Qing Li

### Main results

	Method	GQA	NLVRv2	Editing	Tagging		Method	GQA	NLVRv2
	Otter [27]	48.2	48.2		-		w/o local reflection	52.0	65.2
E2E	MMICL [83]	64.4	62.2				w/o global reflection	53.6	64.2
				-	-	Reflection	w/o intermediate results	48.8	61.2
	GPT4TOOLs [75]	41.2	45.4	17.8			w/o plan	50.0	62.6
	Visual ChatGPT [75]	43.2	51.6	21.7	-		Ours	<b>54.6</b>	65.6
	InternGPT [40]	44.8	39.4	_	_		w/o incorrect cases	46.1	61.4
<b>T</b> 1	<u> </u>					Prompt Engineering	w/o correct cases	48.2	63.2
Tool	HuggingGPT [62]	46.0	44.0	-	-	for LLMs	w/o validation	44.2	61.0
	ViperGPT [67]	47.2	-	-	-		Ours	54.6	<b>65.6</b>
	VISPROG [11]	49.8	60.8	40.2	0.393	Prompt Tuning	w/o validation	42.8	62.8
	CLOVA (Ours)	54.6	65.6	65.4	0.502	for visual tools	Ours	54.6	65.6

### **Different LLMs**

Dataset	Method	LLaMA2-7B	GPT-3.5	GPT-4				<b>D</b> 1' <i>i</i> '	
	Baseline	39.2	46.4	52.6	Method	GQA	NLVRv2	Editing	Ta
GQA	+ Update LLMs	56.8	51.6	56.6	LLama2-7B	39.2	50.0	31.2	0
	+ Update visual tools	60.2	54.6	60.4	LLama2-7B + Ours	<b>60.2</b>	<b>63</b> .8	<b>47.6</b>	0
	Baseline	50.0	60.2	64.8	Mistral-7B	20.4	34.6	29.0	0
NLVRv2	+ Update LLMs	59.2	63.6	68.8	Mistral-7B + Ours	31.4	<b>42.2</b>	<b>46.5</b>	0.
	+ Update visual tools	63.8	65.6	69.2		1			

**Quantitative observation:** □ CLOVA achieves SOTA among tool-usage VLMs. □ CLOVA is robust to different LLMs, including open and closed ones. □ Update both LLM and visual tools bring significant improvements.

Instruction: Replace the bird with pine grosbeak (a kind of Passeriformes) Human feedback : The pine grosbeak in the new generated image is wrong Generated program: Step1: OBJ0=SEG(image=IMAGE) Step2: OBJ1=SELECT(image=IMAGE,object=OBJ0,query='bird',category=None) Step3: IMAGE0=REPLACE(image=IMAGE,object=OBJ1,prompt='pine grosbeak') Step4: FINAL_RESULT=RESULT(var=IMAGE0) Intermediate results: Step1: The coordinate of OBJ0: [[0, 0, 639, 399], [294, 358, 639, 399], [252, <u>62</u> , 449, 395]] Step2: The coordinate of OBJ1: [[252, <u>62</u> , 449, 395]] Step3: The description of IMAGE0: a photography of a spiky plant on a rock in the woods Step4: The description of FINAL_RESULT: a photography of a spiky plant on a rock in the woods		Reflection for the REPLACE tool in an image editing task
Step1: OBJ0=SEG(image=IMAGE)Step2: OBJ1=SELECT(image=IMAGE,object=OBJ0,query='bird',category=None)Step3: IMAGE0=REPLACE(image=IMAGE,object=OBJ1,prompt='pine grosbeak')Step4: FINAL_RESULT=RESULT(var=IMAGE0)Intermediate results:Step1: The coordinate of OBJ0: [[0, 0, 639, 399], [294, 358, 639, 399], [252, 62, 449, 395]]Step2: The coordinate of OBJ1: [[252, 62, 449, 395]]Step3: The description of IMAGE0: a photography of a spiky plant on a rock in the woodsStep4: The description of FINAL_RESULT: a photography of a spiky plant on a		
<b>Step1:</b> The coordinate of OBJ0: [[0, 0, 639, 399], [294, 358, 639, 399], [252, <u>62</u> , 449, 395]] <b>Step2:</b> The coordinate of OBJ1: [[252, <u>62</u> , 449, 395]] <b>Step3:</b> The description of IMAGE0: a photography of a spiky plant on a rock in the woods <b>Step4:</b> The description of FINAL_RESULT: a photography of a spiky plant on a	Step1: OE Step2: OE Step3: IM	BJ0=SEG(image=IMAGE) BJ1=SELECT(image=IMAGE,object=OBJ0,query='bird',category=None) AGE0=REPLACE(image=IMAGE,object=OBJ1,prompt='pine grosbeak')
	Step1: TI 449, 395] Step2: TI Step3: TI he wood Step4: TI	he coordinate of OBJ0: [[0, 0, 639, 399], [294, 358, 639, 399], [252, <u>62</u> , ] he coordinate of OBJ1: [[252, <u>62</u> , 449, 395]] he description of IMAGE0: a photography of a spiky plant on a rock in s he description of FINAL_RESULT: a photography of a spiky plant on a

We build **CLOVA**, the first VLM that can **improve from feedback** via a closed-loop learning framework with **inference**, **reflection**, **learning** phases. Use both correct and incorrect examples for prompts to generate plans & programs. □ Propose a global-local reflection scheme to diagnose errors. □ Apply hard/soft prompt tuning to update tools with limited data. **Code & Examples**: <u>clova-tool.github.io</u>

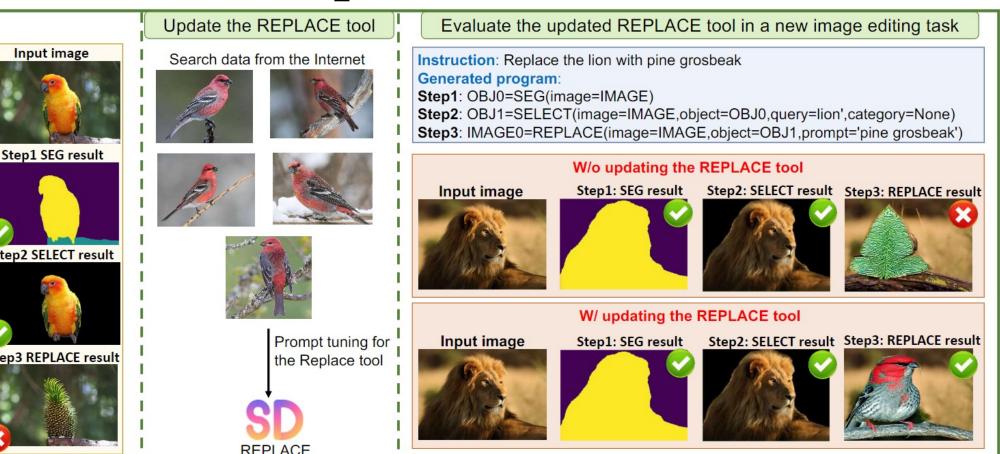




### Experiments

### **Ablation studies**

### ualitative example



## **Takeaway Message**